# Learning Representations of Student Knowledge and Educational Content

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## Motivation

# How can we guide students through large, heterogeneous collections of educational content to help them achieve their goals?

- Content = lessons and assessments
- Goal = passing an assessment
- Guide = recommending personalized lesson sequences



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# General Approach

- 1. Alice completed Lesson B
- 2. Alice passed Assessment C
- 3. Alice failed Assessment D
- 4. Alice completed Lesson E
- 5. Alice passed Assessment D

- 1. Bob completed Lesson B
- 2. Bob failed Assessment C
- 3. Bob failed Assessment D
- 4. Bob completed Lesson E
- 5. Bob passed Assessment C



#### Related Work

### Related Work

Existing frameworks:

- Bayesian Knowledge Tracing (BKT)
- ▶ Item Response Theory (IRT)
- Sparse Factor Analysis (SPARFA)

	knowledge tracing	lesson effects	evaluations
DKT	RNN	-	outcome prediction
T-SKIRT	input-output HMM	-	outcome prediction
SPARFA-Trace	input-output HMM	skill gains	outcome prediction
Embodding	input output HMM	skill gains,	outcome prediction,
Lungading		prereqs	lesson recommendation



#### Formulation

## Student and Content Representations

- Student = a set of latent skill levels that vary over time
- Lesson module = a vector of skill gains, and a set of prerequisite skill requirements
- Assessment module = a set of skill requirements
- A student can be tested on an assessment module, which has a pass-fail result. The likelihood of passing should be high when a student has skill levels that exceed the assessment requirements, and vice-versa.
- A student can complete lesson modules to learn over time, though the skill gains from a lesson module are modulated by prerequisite knowledge



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#### Formulation

# Modeling Assessment Outcomes

For student  $\vec{s}_t \in \mathbb{R}^d$ , assessment  $\vec{a} \in \mathbb{R}^d$ , and result  $R \in \{0, 1\}$ ,

 $R \sim \text{Bernoulli}(\phi(\Delta(\vec{s_t}, \vec{a})))$ 

where  $\phi$  is the logistic function and  $\Delta(\vec{s_t}, \vec{a}) = \frac{\vec{s_t} \cdot \vec{a}}{||\vec{a}||} - ||\vec{a}|| + \gamma_s + \gamma_a$ 





Formulation

# Modeling Student Learning from Lessons

For student  $\vec{s}_t \in \mathbb{R}^d$  who worked on <sup>S</sup> a lesson with skill gains  $\vec{\ell} \in \mathbb{R}^d_+$  and no prerequisites at time t + 1, the updated student state is

 $ec{s_{t+1}} \sim \mathcal{N}\left(ec{s_t} + ec{\ell}, \Sigma
ight)$ 

where the covariance matrix  $\Sigma = I_d \sigma^2$  is diagonal. For a lesson <sup>Ski</sup> with prerequisites  $\vec{q} \in \mathbb{R}^d$ ,

$$ec{s_{t+1}} \sim \mathcal{N}\left(ec{s_t} + ec{\ell} \cdot \phi(\Delta(ec{s_t}, ec{q})), \Sigma
ight)$$

where  $\Delta(ec{s_t},ec{q}) = rac{ec{s_t}\cdotec{q}}{||ec{q}||} - ||ec{q}||$ 



# **One-Dimensional Embedding**



# Two-Dimensional Embedding



Examples

# Embedding with Lessons



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# Embedding with Lesson Prerequisites



#### Data

# Online Course Data

The two data sets from Knewton collectively contain

- 2,184,352 interaction logs
- 1,939 classrooms
- 6 months
- 7,034 students
- 7,217 lessons
- 7,287 assessments
- Average assessment pass rates of 0.712 and 0.693



### Parameter Estimation

We compute MAP estimates of model parameters Θ by maximizing

$$L(\Theta) = \sum_{\mathcal{A}} \log \left( \Pr(R \mid \vec{s}_t, \vec{a}, \gamma_s, \gamma_a) \right) \\ + \sum_{\mathcal{L}} \log \left( \Pr(\vec{s}_{t+1} \mid \vec{s}_t, \vec{\ell}, \vec{q}) \right) - \beta \cdot \lambda(\Theta)$$

where  $\mathcal{A}$  is the set of assessment interactions,  $\mathcal{L}$  is the set of lesson interactions,  $\lambda(\Theta)$  is a regularization term that penalizes the  $L_2$  norms of embedding parameters (not bias terms  $\gamma$ ), and  $\beta$  is a regularization parameter.

Solved with L-BFGS-B and random parameter initializations



- Hold out assessment interactions at the end of student histories
- Area under ROC Curve (AUC)
- Ten-fold cross-validation



	d	5	а	$\ell$	q	$\gamma$	Training	Validation
1	1	Υ	Ν	Ν	Ν	Ν	0.723	0.686
2	1	Ν	Υ	Ν	Ν	Ν	0.715	0.661
3	2	Υ	Υ	Ν	Ν	Ν	0.991	0.614
4	2	Υ	Υ	Ν	Ν	Y	0.992	0.726
5	2	Y	Y	Y	Ν	Ν	0.897	0.696
6	2	Y	Y	Y	Ν	Y	0.871	0.748
7	2	Υ	Υ	Y	Υ	Ν	0.898	0.694
8	2	Y	Y	Y	Y	Y	0.882	0.749

Joint embedding beats baselines

Including lesson embeddings improves performance significantly

- Including prerequisite embeddings has a statistically insignificant effect on performance
- Including bias terms improves performance significantly



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Expected relative gain from taking recommended path

$$\mathbb{E}\left[rac{\mathbb{E}[R']-\mathbb{E}[R]}{\mathbb{E}[R]}
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where R' is the outcome at the end of the recommended path and R is the outcome at the end of the other path

Propensity score matching

- Student features = past outcomes
- Logistic regression for propensity score estimation
- Nearest neighbor matching



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#### Summary

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- Demonstrated the ability of an embedding model to successfully predict assessment results
  - Modeling skill gains from lessons is helpful
  - Modeling prerequisites for lessons is not helpful
- Introduced an offline methodology as a proxy for assessing the ability of a model to recommend personalized lesson sequences
  - Embedding model can distinguish between "good" and "bad" paths in bubble scenarios



# **Ongoing Work**

- Cold Start Problem
  - Impose prior distribution on content embeddings based on content-to-concept map and concept dependency graph made by experts
- Personalized Scheduling
  - Jointly model assessment results, response times, and number of attempts
  - Model the forgetting effect and offline learning between interactions
  - Handle wall-clock time constraints on recommended sequences
- Content Analytics
  - Small-scale Mechanical Turk experiments for teaching basic programming
  - Measure lesson quality



#### Contact

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